A reduced form multivariate quantile autoregressive model is developed to study heterogeneity in the effects of macroeconomic shocks. This framework is used for forecasting and for constructing quantile impulse response functions that explore dynamic heterogeneity in the response of endogenous variables to different shocks. The methodology allows evaluating different quantile paths, defined as the dynamic effects for a fix collection of quantile indexes. The model is applied to study monetary shocks in a three-variable macroeconomic model (output gap, inflation, Fed Funds rate) for the USA for the period 1980q1–2010q1.

Received 31 October 2017; Accepted 10 January 2019

Keywords: Multivariate quantiles; multivariate time-series; vector autoregression; impulse response functions.

JEL. C13; C14; C42

MOS Subject Classification: 62H05, 62M10, 91B84.

1. INTRODUCTION

An important way to summarize the dynamics of macroeconomic data is to make use of a vector autoregressive (VAR) model. The VAR approach provides statistical tools for data description, forecasting, and structural inference to study rich dynamics in multivariate time-series models.

Nevertheless, the use of a constant-coefficient model as representative of time-series models may not be adequate, as these models ignore the effects that a succession of small and varied shocks may have on the structure of dynamic economic models, particularly for highly aggregated data series. Moreover, these models cannot appropriately account for the presence of asymmetric and heterogeneous dynamic responses. Of particular interest is the asymmetric business cycle dynamics of economic variables, as the occurrence of asymmetries may call into question the usefulness of models with time invariant structures as means of modeling such series.

Quantile regression (QR) is a statistical method for estimating models of conditional quantile functions. This method offers a systematic strategy for examining how covariates influence the location, scale, and shape of the entire response distribution, thereby exposing a variety of heterogeneity in response dynamics. Koenker and Xiao (2006) examine the implications of QR models in time-series. Galvao et al. (2013) interpret the QR time-series framework as modeling the business cycle, where high (low) conditional realizations of a distributed lag model correspond to high (low) quantiles.

Montes-Rojas (2017) develops a reduced form vector directional quantile estimator based on the multivariate directional quantiles framework of Hallin et al. (2010). We apply this estimator to a VAR time-series multivariate model, the vector autoregressive quantile (VARQ) model, which generalizes the quantile autoregressive framework proposed by Koenker and Xiao (2006) and Galvao et al. (2013) to the multivariate case. The proposed model is a solution to a collection of directional quantile models for a fixed orthonormal basis, in which each component
represents a directional quantile that corresponds to a particular endogenous variable. The directional quantile theory shows that once a direction is fixed, quantile models are well defined. The model delivers a map from the space of the $\sigma$-field generated by the information available at a particular time and a unit ball whose dimension is given by the number of endogenous variables to the space of endogenous variables. The VARQ estimator explores heterogeneity in time-series by estimating conditional models of each endogenous variable conditional on all other contemporaneous endogenous variables and the set of information available at the time. These conditional models are used to construct a simultaneous system of directional QR models, whose solution is a reduced-form multivariate quantile model.

The VARQ estimator allows us to forecast the future performance of the multivariate time-series, which depends on multivariate quantile indexes. This corresponds to the forecasting of the multivariate density of endogenous variables conditional on the available information. From the forecasting procedure we define an impulse response function (IRF) model that computes the effect of a given perturbation in one or more variables on the entire system, the quantile IRF (QIRF). This procedure explores potential dynamic heterogeneity not covered by the mean-based IRF analysis using mean-based VAR. In particular, we can study the realization of particular sequences of events by analyzing the multivariate quantile indexes, defined as quantile paths.

The proposed framework is different from recent attempts to construct heterogeneous IRFs. Chavleishvili and Manganelli (2016) accommodates a bivariate system of dynamic conditional quantiles of random variables where one of the random variables evolves exogenously to the system. They provide the statistical framework to define structural quantile shocks and the associated quantile IRFs using a multivariate generalized autoregressive conditional heteroskedasticity framework.

We estimate the VARQ and perform QIRF analysis using a three-variable macroeconomic model for the USA, with output gap, inflation and Fed Funds rate, for the period 1980q1–2010q4. We then evaluate the effect of a standard deviation shock in the interest rate, that is, the monetary shock using the Cholesky decomposition of Christiano et al. (1996), and explore dynamic heterogeneity applying the QIRFs. This new analysis reveals important asymmetries and heterogeneity in the response to monetary shocks in terms of different quantile paths of high or low conditional output and inflation.

The article is organized as follows. Section 2 presents the theory of directional quantiles and the definition of the VARQ model. Section 3 develops forecasting procedures using VARQ, and Section 4 develops QIRF. Section 5 shows the application of the VARQ and QIRF models to empirical series. Section 6 concludes.

2. VARQ MODEL

For a given cumulative distribution function $F_Y$ of a univariate random variable $Y$, the univariate quantile function is well defined. In particular, the $\tau$-quantile for $\tau \in (0, 1)$ is defined as $Q_Y(\tau) = \inf \{ y \in Y : \tau \leq F_Y(y) \}$, and if $F_Y$ is continuous, then $Q_Y(\tau) = F_Y^{-1}(\tau)$. In the multivariate case, however, there is no unique definition of a multivariate quantile function.

There is a growing literature on the estimation of QR models for multivariate random variables. Hallin et al. (2010) and Paindaveine and Šiman (2011, 2012) build on the definition of directional quantiles, whereby quantiles are equipped with a directional vector. Distributional features are thus explored by considering different directional models; see also Fraiman and Pateiro-López (2012) for related work. Wei (2008) develops a bivariate quantile model, following the marginal-conditional structure of Ma and Koenker (2006). White et al. (2015) develop an autoregressive model of the quantiles themselves, extending the CAViaR model of Engle and Manganelli (2004) to the multivariate case. In related work, Han et al. (2016) study quantile dependence among time-series models. Carlier et al. (2016) propose a vector QR (linear) model that produces a monotone map, the gradient of a convex function. In a more general setup, Chernozhukov et al. (2015) develop a concept of multivariate quantile based on transportation maps between a distribution of interest with a domain in multivariate real numbers and a unit ball of the same dimension. Finally, another approach is to use copula-based quantile models, as any multivariate distribution can be decomposed into its marginals and a dependence function or copula; see, for example, Bernard and Czado (2015); however, such an approach requires imposing distributional assumptions.
Consider an \(m\)-dimensional process \(Y_t = (Y_{1t}, \ldots, Y_{mt})^\top\) and assume that for all \(t \in \{0, 1, \ldots\}, Y_t \in \mathcal{Y} \subseteq \mathbb{R}^m\). Further, consider a \(k \times 1\) vector of covariates \(X_t \in \mathcal{X} \subseteq \mathbb{R}^k\). Of particular interest is the case of the covariates generated by the \(s\)-field given by \(\{Y_s : s < t\}\) and all other information available at time \(t\). One then deals with a VARQ quantile model. For an autoregressive model of order \(p\), \(X_{t-1} = (Y_{t-1}^\top, \ldots, Y_{t-p}^\top)^\top\) and \(k = mp\). We can then index VARQ models according to the lag order, that is, VARQ(\(p\)).

Let the vector \(\tau = (\tau_1, \ldots, \tau_m)\) be an index of the \(\mathbb{R}^m\) space, which is an element of the open unit ball in \(\mathbb{R}^m\) (deprived of the origin) \(T^m = \{z \in \mathbb{R}^m : 0 < \|z\| < 1\}\), where \(\|\cdot\|\) denotes the Euclidean norm. Montes-Rojas (2017) considers the reduced form vector directional quantile (VDQ) model given by

\[
Q_{\mathcal{Y}}(\tau|X_{t-1} = x_{t-1}) = B(\tau)x_{t-1} + A(\tau),
\]

where \(Q\) is an \(m \times 1\) vector, which corresponds to the multivariate quantiles of the \(m\) random variables, \(B(\tau) = (B_1(\tau), \ldots, B_m(\tau))^\top\) is an \(m \times k\) matrix of coefficients with \(B_j(\tau)\) for each \(j \in \{1, \ldots, m\}\), \(k \times 1\) vector of coefficients of the \(j\)th element in \(Y\), and \(A(\tau)\) is an \(m \times 1\) vector of coefficients. Moreover, let \(B_{jh}(\tau) = (B_{1h}(\tau), \ldots, B_{mh}(\tau))\) the \(h\)-lag coefficients for all endogenous variables models, for \(h = 1, \ldots, p\). Thus, \(Q\) is a map \(\mathcal{X} \times T^m \mapsto \mathcal{Y}\). The VDQ applied to an autoregressive context is thus our proposed model for VARQ.

For the time-series context we can define the lag polynomials \((B(\tau), L))\) where \(L\) is the lag operator, such that

\[
B(\tau)X_{t-1} = B(\tau, L)Y_t = \sum_{h=1}^{p} B_h(\tau)L^hY_t
\]

and

\[
Q_{\mathcal{Y}}(\tau|X_{t-1} = x_{t-1}) = B(\tau, L)y_t + A(\tau).
\]

where \(y_t\) denotes the values of \(Y_t\) to be used in the equation.

To construct the VARQ model, define \(Q_{\mathcal{Y}}(\tau|X_{t-1}) := \{q_1(\tau|x_{t-1}), \ldots, q_m(\tau|x_{t-1})\}^\top\) from the following system of equations,

\[
\begin{align*}
q_1(\tau|x_{t-1}) & := c_1(\tau_1)^\top q_{1}(\tau|x_{t-1}) + b_1(\tau_1)^\top x_{t-1} + a_1(\tau_1) \\
& \vdots \\
q_m(\tau|x_{t-1}) & := c_m(\tau_m)^\top q_{m}(\tau|x_{t-1}) + b_m(\tau_m)^\top x_{t-1} + a_m(\tau_m),
\end{align*}
\]

where \(\{c_j(\tau_j)\}_{j=1}^{m}\) and \(\{b_j(\tau_j)\}_{j=1}^{m}\) are vectors of dimensions \((m-1) \times 1\) and \(k \times 1\) respectively, and \(\{a_j(\tau_j)\}_{j=1}^{m}\) are scalars. \(\{q_j(\tau|x_{t-1})\}_{j=1}^{m}\) correspond to individual time-series QR models of each \(j\) component, that is, \(Y_{1t}\), on all others \(-j\) components, that is, \(Y_{jt}\), and the lags, that is, \(X_t\), where all the components are simultaneously evaluated at \(Q(\tau|x_{t-1})\) (for further reference, we use the \(-j\) notation to denote a vector or matrix that excludes the \(j\)th column or row). In turn these are obtained using Hallin et al. (2010) directional quantiles for a fix orthonormal basis and the VARQ estimator is a fixed point solution to a system of equations.

Consider the following matrices based on the coefficients of eq. (3): \(C(\tau) := \{C_1(\tau_1), \ldots, C_m(\tau_m)\}^\top\) is an \(m \times m\) matrix in which the \(\{C_j(\tau_j)\}_{j=1}^{m}\) \(m \times 1\)-dimensional vectors contain all the elements of the \(m-1\) vector of coefficients \(\{c_j(\tau_j)\}_{j=1}^{m}\) augmented with \(0\) in the corresponding \(j\)th component, \(b(\tau) = (b_1(\tau_1), \ldots, b_m(\tau_m))^\top\) is an \(m \times k\) matrix, and \(a(\tau) = (a_1(\tau_1), \ldots, a_m(\tau_m))^\top\) is an \(m \times 1\) vector. Then, the VARQ model is defined as

\[
Q_{\mathcal{Y}}(\tau|x_{t-1}) = \{I_m - C(\tau)\}^{-1} \{b(\tau)x_{t-1} + a(\tau)\} := B(\tau)x_{t-1} + A(\tau),
\]

where \(I_m\) is the \(m\)-dimensional identity matrix, \(B(\tau) := \{I_m - C(\tau)\}^{-1} b(\tau)\) and \(A(\tau) := \{I_m - C(\tau)\}^{-1} a(\tau)\). Note that for a fixed \(\tau\) the number of parameters to be estimated is that of a structural mean-based VAR model.
The VARQ model describes the multivariate random variables conditional on the past by way of modeling the simultaneous responses. For each of the \(j\) equations, the \(\tau_i\)-quantile model describes the conditional performance of the \(j\)th endogenous variable conditional on the values of the others and the available past information. \(\tau\) thus represents the individual contribution of every endogenous variable in the system after considering the effects of all the others. Each individual equation corresponds to a quantile autoregressive distributed lag model, see, for example, Galvao et al. (2013). The VARQ model is the simultaneous solution of all equations for the fixed collection of individual univariate quantiles indexed by \(\tau\). As noted by Montes-Rojas (2017) this corresponds to a reduced form VAR model that is a functional in \(\tau\).

Although the VARQ model is constructed for stationary processes, Koenker and Xiao (2004, 2006) consider the case of unit roots in some quantiles and stationarity in others. While we do not pursue the properties of the non-stationary behavior in those cases, the unit root processes can be easily detected by looking at their dynamic behavior.

3. FORECASTING USING VARQ AND QUANTILE PATHS

The VARQ model implicitly defines a one-period ahead forecasting method for the entire distribution of \(Y_{t+1}\) given all the information available at \(t\).

\[
Q_{Y_{t+1}}(\tau | x_t) = Q_{Y_{t+1}}(\tau | y_t, y_{t-1}, \ldots, y_{t-p}) = B(\tau, L)y_{t+1} + A(\tau).
\]

Define thus \(Q_j(\tau | x_t) = Q_{Y_{t+1}}(\tau | x_t)\) as the one-period ahead forecast given all the information available at time \(t\).

Consider now the two-periods ahead forecast, that is \(t + 2\), at quantiles \(\tau_i\). Note that this would depend on the response at \(t + 1\) and the implicit quantile \(\tau_1\). In turn then this would depend on both quantiles, \((\tau_2, \tau_1)\). This is defined as a two-periods quantile path, where the collection of indexes correspond to a potential path of the system of endogenous variables. Then

\[
Q_{2}[(\tau_2, \tau_1)|x_t] := Q[\tau_2][Q[\tau_1]|x_t, y_t, \ldots, y_{t-p+1}].
\]

Replacing for the linear quantile models we have

\[
= B(\tau_2)[Q(\tau_1)|x_t]^\top, y_t^\top, \ldots, y_{t-p+1}^\top]^\top + A(\tau_2) = B(\tau_2)[[B(\tau_1)x_t + A(\tau_1)]^\top, y_t^\top, \ldots, y_{t-p+1}^\top]^\top + A(\tau_2).\]

In particular for the VARQ(1) model

\[
Q_{2}[(\tau_2, \tau_1)|x_t] = B(\tau_2)B(\tau_1)x_t + B(\tau_2)A(\tau_1) + A(\tau_2).
\]

The \(h\)-periods ahead forecast can be written as a function of the forecast of the previous quantiles,

\[
Q_h[(\tau_h, \ldots, \tau_1)|x_t] = B(\tau_h, L)Q_h[(\tau_k, \ldots, \tau_1)|x_t] + A(\tau_h),
\]

where \(Q_k[.] = y_{t-k}\) if \(L^k(t + h) \leq t\) and \((\tau_k, \ldots, \tau_1), k = 1, \ldots, h - 1\) is the \(k\)-periods quantile path. Then we can write

\[
Q_h[(\tau_h, \ldots, \tau_1)|x_t] = [\prod_{k=1}^{h-1} B(\tau_k)]x_t + \sum_{j=1}^{h-1} [\prod_{k=j+1}^{h} B(\tau_j)]A(\tau_k) + A(\tau_h).
\]

This framework allows for forecasting different quantile paths.

A canonical case is fixing \(\tau_i = (0.5, \ldots, 0.5)\) for all \(i = 1, \ldots, h\), which corresponds to evaluating future values on the conditional median values of the endogenous variables. In general this procedure delivers similar estimates.
to the mean-based VAR forecasts. In this case each realization is evaluated at the conditional median and the $h$-periods ahead forecast is also constructed using $h = 1, \ldots, 1$ values at the median.

This procedure can be generalized for any $\tau_i = (\tau, \ldots, \tau)$ for all $i = 1, \ldots, h$. In this case high values of $\tau$ correspond to the persistent occurrence of the $\tau$ conditional quantile in all endogenous variables. Moreover, we do not necessarily need the same $\tau$ for all endogenous variables equations. As an example in the empirical application we consider the 0.1 and 0.9 quantiles of output, while we keep the median for inflation and interest rate. As such, we are constructing a potential quantile path where output is either at the low or high end of the business cycle. See Galvao et al. (2013) for an interpretation of QR time-series models in terms of the business cycle.

Note, however, that if we are interested in the $h$-periods ahead forecast, this may not depend on the implicit quantile used for the $k$-step forecast, $k < h$. As such we could integrate out $\tau_i$ by using $\tau_k \sim i.i.d.$ $U(0, 1)^m$ for $k = 1, 2, \ldots, h - 1$. Define $\tilde{B} = E_\tau B(\tau)$ and $\tilde{A} = E_\tau A(\tau)$. Then,

$$Q(\tau|x) = B(\tau)\tilde{B}^{-1} x + B(\tau) \left\{ \sum_{k=1}^{h-1} \tilde{B}^{-1} \tilde{A} \right\} + A(\tau).$$

As $h \to \infty$, the long run prediction converges to

$$\lim_{h \to \infty} Q(\tau|x) = B(\tau)(I - \tilde{B})^{-1} \tilde{A} + A(\tau).$$

Note that $\tilde{B}$ and $\tilde{A}$ are not necessarily equal to the mean-based reduced form VAR coefficients. Following Koenker and Xiao (2006) we could write a random-coefficients representation of model (3) for which integrating out the quantiles produces the mean-based model. However, the VARQ model is a non-linear transformation of (3) and quantile operators cannot be applied to non-linear functions.

### 4. SHOCKS AND IRFS IN THE VARQ MODEL

#### 4.1. Impulse Responses from VARQ

Ramey (2016) defines shocks as *primitive exogenous* forces that are uncorrelated with each other and that are *economically meaningful* (pp. 52–5). Shocks have the following characteristics: (i) they should be exogenous with respect to the other current and lagged endogenous variables in the model; (ii) they should be uncorrelated with other exogenous shocks (...); (iii) they should represent either unanticipated movements in exogenous variables or *news* about future movements in exogenous variables. The literature on measuring shocks on time-series models is based on VAR models, where a shock refers to a change in the residual of a conditional model, and in identifying exogenous changes in a structural model. See Ramey (2016); Stock and Watson (2016) for a recent literature review that resumes the state of the art.

By modeling the multivariate quantiles we do not have a structural model nor we have a system of residuals in a reduced form additive model, but rather we replicate the simultaneous movements in the endogenous variables by way of indexing them by $\tau$. The VARQ is a reduced-form model, and then it is adequate for forecasting and impulse response analysis, once shocks have been constructed from some other mechanism, probably based on mean-based structural VAR. Then we compute a counterfactual change $\Delta \in \mathcal{Y} \subseteq \mathbb{R}^m$ in $y$. Our interest lies in evaluating the propagation of those shocks in terms of the multivariate distribution of the m-variate process. We then compute the IRF by comparing the multivariate quantiles at $x^\Delta := (y, \Delta, y_{t-1}, \ldots, y_{t-p})$ with those at $x_t = (y_t, y_{t-1}, \ldots, y_{t-p})$.

Define the $\tau$-quantile IRF (QIRF) at $t + 1$ for a shock at time $t$, $\delta \in \mathcal{Y} \subseteq \mathbb{R}^m$, as

$$Q_{\tau}(\tau, \delta|x_t) = Q_\tau(\tau|x^\Delta) - Q_\tau(\tau|x_t) = B_{\tau}(\tau)\delta,$$

where $Q_\tau$ is the one-period ahead forecast.
Consider now the IRF two-periods ahead, that is, $t + 2$, at quantiles $\tau_2$. Note that this would depend on the response at $t + 1$ and the implicit quantile $\tau_1$. In turn then this would depend on both quantiles, $(\tau_2, \tau_1)$, defined as a quantile path.

$$\text{Qirf}_{2(1)} \{ (\tau_2, \tau_1), \delta | x_t \} = Q_2 \{ (\tau_2, \tau_1) | x_t^\delta \} - Q_2 \{ (\tau_2, \tau_1) | x_t \} = \begin{cases} (B_2(\tau_2) + B_1(\tau_1) \tilde{B}) \delta & p > 1 \\ \tilde{B}_1(\tau_2) \tilde{B}_1(\tau_1) \delta & p = 1 \end{cases}.$$ 

The QIRF above is constructed for different quantile paths, where each forecast is evaluated at a given multivariate quantile index, and for a fixed quantile index used for the previous endogenous variables forecasts.

Note however that if we are interested in the two-periods ahead forecast, this may not depend on the implicit quantile used for the one-step forecast. As such we could integrate out $\tau_1$ by using $\tau_1 \sim U(0,1)^m$. Then define

$$\text{Qirf}_{2(1)}(\tau, \delta | x_t) = Q_2(\tau | x_t^\delta) - Q_2(\tau | x_t) = \begin{cases} (B_2(\tau) + B_1(\tau) \tilde{B}) \delta & p > 1 \\ B_1(\tau) \tilde{B} \delta & p = 1 \end{cases}.$$ 

The difference between Qirf$_{2(1)}$ and Qirf$_2$ is that the former corresponds to a particular path of assumed realizations of the multivariate process, while the latter focuses on the distribution two-periods ahead for a forecasted value of one-period ahead.

This procedure above can be generalized for $h$-periods ahead IRFs, by defining

$$\text{Qirf}_{h(1, \ldots, 1)} \{ (\tau_h, \tau_{h-1}, \ldots, \tau_1), \delta | x_t \} = Q_h \{ (\tau_h, \tau_{h-1}, \ldots, \tau_1) | x_t^\delta \} - Q_h \{ (\tau_h, \tau_{h-1}, \ldots, \tau_1) | x_t \}, \tag{5}$$

for a given path of multivariate quantiles $(\tau_h, \tau_{h-1}, \ldots, \tau_1)$ and shock $\delta$ at time $t$, and

$$\text{Qirf}_h(\tau, \delta | x_t) = Q_h(\tau | x_t^\delta) - Q_h(\tau | x_t). \tag{6}$$

when we integrate out the previous periods that were constructed by iterations. This is different from the mean-based VAR analysis. In this case, by using the iterated expectations property, the effect on $h$ periods ahead is the result of the conditional expectations in the previous periods.

In the long run the QIRF for $h \to \infty$ becomes 0 for stationary models.$^1$

A simple simulation exercise appears in the Appendix to illustrate the QIRF model.

### 4.2. Local Projections

A robust model for constructing IRFs is based on Jordà (2005) local projections method. The central idea consists in estimating local projections at each period of interest (i.e. $t + h$) rather than extrapolating into increasingly distant horizons from a given model, as it is done with VAR. The advantages of local projections are numerous: (i) they can be estimated by simple regression techniques; (ii) they are more robust to misspecification; (iii) joint or point-wise analytic inference is simple; and (iv) they easily accommodate experimentation with highly nonlinear and exible specifications that may be impractical in a multivariate context.

---

$^1$ The Enders’ book (2005, Chapter 5) has an intuitive explanation for the fact that IRF needs to become 0 as $h \to \infty$. For stationary models the IRF is the collection of the effects of a variable $j$ in a variable $k$ (for all $j, k$) that occurred at some point $h = 0$ on a different time path $h = 0, 1, \ldots$. These effects have to converge to 0 as $h$ gets larger because ‘shocks cannot have a permanent effect on a stationary series’ (Enders, 2005, p. 295). The reason is that ‘[j]ust as an autoregression has a moving average representation, a vector autoregression can be written as a vector moving average (...) [where the model is] expressed in terms of the current and past values of the (...) shocks’ (Enders, 2005, p. 295). This invertibility condition can only be achieved if the effects of past shocks is smaller as we consider longer horizons.
This framework can be easily implemented in a VARQ context by modeling the VDQ model of $Y_{t+h}$ at each horizon $h = 1, 2, \ldots$ given all the information available at $t$, that is, all the lags of the endogenous variables up to $t$ (plus exogenous variables if any)

$$Q_h^{\mu}(\tau|x_t) := Q_{Y_{x+h}}(\tau|x_t) = B_h(\tau)x_t + A_h(\tau).$$  \hspace{1cm} (7)

Note that in this case we require to solve a different set of coefficients for each horizon $h$, which in fact involves directional QR models involving regressing $Y_{j+t+h}$ on $Y_{-j+t+h}$ and $x_t$, for $j = 1, \ldots, m$. Then we could construct the QIRFs as

$$Q_{\text{IRF}}^h(\tau, \delta|x_t) = Q_h^{\mu}(\tau|x^\delta_t) - Q_h^{\mu}(\tau|x_t).$$  \hspace{1cm} (8)

While this is an important alternative for prediction, it does not allow us to study quantile paths. That is, intermediate realizations of the random variables, that is, for $h - 1, h - 2, \ldots, 1$, are implicitly evaluated at the mean-based values.

5. HETEROGENEITY OF MONETARY SHOCKS

We estimate a three-variable (output gap, inflation, Fed Funds rate) VAR(1) model using US quarterly data from 1980q1 to 2010q1 (121 quarters). This simple framework corresponds to the three-variable framework of New Keynesian model rational expectations model of Cho and Moreno (2004, 2006) and Jordà (2005), among others. We do not impose a structural model but rather we consider a simple unrestricted VAR model of order 1 of the three variables. The period is chosen to cover the post-Volcker Fed rules and previous to the zero lower bound, post-financial crisis regime.

The output gap is generated by the first-difference of the Hodrick-Prescott linear filter with linear trend, using the logarithm of the Gross National Product, 1996 constant prices (source: Federal Reserve Bank of St. Louis), denoted $y_t$. The inflation rate is the log first-difference of the GDP deflator, seasonally adjusted (source: Federal Reserve Bank of St. Louis), denoted $\pi_t$. The Fed Funds rate is the monetary policy instrument (source: Board of Governors of the Federal Reserve System), denoted $r_t$, and corresponds to the first-difference of the 3-months Treasury Bill rate (end of the quarter). The reason we use the first-difference of the interest rate is that over the period of analysis it shows a negative trend and we cannot reject it has a unit root. For this case then $Y_t = (y_t, \pi_t, r_t)$. Figure 1 plots the series considered here, and Table I reports summary statistics.

Figure 2 reports the effect of a unit change in $r$ keeping $(y, \pi)$ unchanged, on the coefficients $B_{(\pi,r)}(\tau, \tau_x, \tau_r)$, denoted as $bplr$ in the figure, and $B_{(y,r)}(\tau, \tau_x, \tau_r)$ denoted as $bylr$ in the figure. We also include the ordinary...
Table I. Summary statistics for the series 1980q1–2010q1

<table>
<thead>
<tr>
<th>Variable</th>
<th>Obs</th>
<th>Mean</th>
<th>Std. Dev.</th>
<th>Min</th>
<th>Max</th>
</tr>
</thead>
<tbody>
<tr>
<td>y</td>
<td>121</td>
<td>−0.00034663</td>
<td>0.0072249</td>
<td>−0.0281541</td>
<td>0.0158011</td>
</tr>
<tr>
<td>π</td>
<td>121</td>
<td>0.0072152</td>
<td>0.0047343</td>
<td>−0.0016704</td>
<td>0.0272542</td>
</tr>
<tr>
<td>r</td>
<td>121</td>
<td>−0.00962</td>
<td>0.0093464</td>
<td>−0.0514</td>
<td>0.0356</td>
</tr>
</tbody>
</table>

Correlations (\(y_t, \pi_t, r_t\))

<table>
<thead>
<tr>
<th>Variable</th>
<th>(y_t)</th>
<th>(\pi_t)</th>
<th>(r_t)</th>
</tr>
</thead>
<tbody>
<tr>
<td>(y_t)</td>
<td>1.0000</td>
<td></td>
<td></td>
</tr>
<tr>
<td>(\pi_t)</td>
<td>−0.1068</td>
<td>1.0000</td>
<td></td>
</tr>
<tr>
<td>(r_t)</td>
<td>0.3831</td>
<td>0.1275</td>
<td>1.0000</td>
</tr>
</tbody>
</table>

Correlations (\(y_t, \pi_t, r_t\)) mean-based VAR residuals

<table>
<thead>
<tr>
<th>Variable</th>
<th>(y_t)</th>
<th>(\pi_t)</th>
<th>(r_t)</th>
</tr>
</thead>
<tbody>
<tr>
<td>(y_t)</td>
<td>1.0000</td>
<td></td>
<td></td>
</tr>
<tr>
<td>(\pi_t)</td>
<td>−0.0023</td>
<td>1.0000</td>
<td></td>
</tr>
<tr>
<td>(r_t)</td>
<td>0.3329</td>
<td>0.0593</td>
<td>1.0000</td>
</tr>
</tbody>
</table>

Figure 2. VARQ coefficients for \(\tau_y \in \{0.05, 0.10, \ldots, 0.95\}\), \(\tau_\pi \in \{0.05, 0.10, \ldots, 0.95\}\) and \(\tau_r = 0.50\). Notes: The figure reports the heterogeneity in the effect of the QR coefficient of a lagged change in the interest rate on output (bylr, horizontal axis) and inflation (bplr, vertical axis). Vertical and horizontal lines correspond to the mean-based VAR effects. Lines with small triangles symbols correspond to VARQ coefficients with \(\tau_y = 0.05\), \(\tau_\pi \in \{0.05, 0.10, \ldots, 0.95\}\), \(\tau_r = 0.50\); small squares \(\tau_y = 0.50\), \(\tau_\pi \in \{0.05, 0.10, \ldots, 0.95\}\), \(\tau_r = 0.50\); small diamonds \(\tau_y = 0.95\), \(\tau_\pi \in \{0.05, 0.10, \ldots, 0.95\}\), \(\tau_r = 0.50\); large triangles \(\tau_y \in \{0.05, 0.10, \ldots, 0.95\}\), \(\tau_\pi = 0.05\), \(\tau_r = 0.50\); large squares \(\tau_y \in \{0.05, 0.10, \ldots, 0.95\}\), \(\tau_\pi = 0.50\), \(\tau_r = 0.50\); and large diamonds \(\tau_y \in \{0.05, 0.10, \ldots, 0.95\}\), \(\tau_\pi = 0.9\), \(\tau_r = 0.50\)

least squares (OLS) estimate given by a regression model of \(y_t\) and \(\pi_t\) on \((y_{t-1}, \pi_{t-1}, r_{t-1})\). We consider different specifications with \(\tau_y \in \{0.05, 0.10, \ldots, 0.95\}\), \(\tau_\pi \in \{0.05, 0.10, \ldots, 0.95\}\) and \(\tau_r = 0.50\) for which we evaluate the effect of a unit change in \(r\).

Figure 2 unmasks interesting heterogeneity in the responses of output and inflation to changes in the interest rate. In particular, note that while OLS and median effects are small, the highest effects correspond to low \(\tau_y\) and \(\tau_\pi\) quantiles.

Next we compute IRFs. We follow the Cholesky identification procedure in Christiano et al. (1996), using the residuals from a VAR model where we assume the standard ordering: \(r\) has no contemporaneous effect on \(y\) and \(\pi\); \(\pi\) has an effect on \(r\) but not on \(y\); and \(y\) affects both \(\pi\) and \(r\). This implies that shocks to the Fed Funds rate has no
contemporaneous effect on the other economic variables. Then we evaluate the effect of a shock in $r$, calculated as the standard deviation of this structural shock, on output gap and inflation (also standardized by the standard deviation of their corresponding structural shocks).

Figures 3 and 4 plot the QIRF of this $r$ shock on output gap and inflation dynamics for the VAR-OLS model and for indexes $\tau = (\tau_y, \tau_x = 0.50, \tau_r = 0.50)$ with $\tau_y = 0.10, 0.50, 0.90$ for the former and $\tau = (\tau_y = 0.50, \tau_x, \tau_r = 0.50)$ with $\tau_x = 0.10, 0.50, 0.90$. The quantile curves thus represent the potential response of $y$ and $\pi$ if the VARQ model is evaluated at fixed $\tau$ for all $h = 1, 2, \ldots, 20$. Note, for example for Figure 3, that the case with $\tau_y = 0.10$ corresponds to the simulation of what would be the response of output and inflation to a change in the interest rate (only) if output response were to remain at the bottom 10% conditional quantile. This indeed corresponds to an extreme event as persistent low quantiles would be associated with an unusual depression (as per the 1980-2010 sample). Moreover, the case with $\tau_x = 0.90$ correspond to a case of output response always in the upper 10% conditional quantile, an extraordinary growth as compared to the estimation sample. Moreover, for Figure 4, the analysis correspond to the case of persistent conditional high ($\tau_x = 0.90$) or low ($\tau_x = 0.10$) inflation.
Figure 4. QIRF for different $\tau_p$. Notes: QIRF on output gap and inflation of a std.dev. shock in $r_t$ for $\tau_p \in \{0.10, 0.50, 0.90\}$, $\tau_y = 0.50$ and $\tau_r = 0.50$

Table II. VAR system stability

<table>
<thead>
<tr>
<th>Model</th>
<th>Eigen 1</th>
<th>Eigen 2</th>
<th>Eigen 3</th>
</tr>
</thead>
<tbody>
<tr>
<td>VAR - OLS</td>
<td>0.853</td>
<td>0.152</td>
<td>0.067</td>
</tr>
<tr>
<td>VARQ ($\tau_y = 0.5, \tau_r = 0.1, \tau_r = 0.5$)</td>
<td>0.669</td>
<td>0.131</td>
<td>0.131</td>
</tr>
<tr>
<td>VARQ ($\tau_y = 0.1, \tau_r = 0.5, \tau_r = 0.5$)</td>
<td>0.813</td>
<td>0.535</td>
<td>0.054</td>
</tr>
<tr>
<td>VARQ ($\tau_y = 0.5, \tau_r = 0.5, \tau_r = 0.5$)</td>
<td>0.818</td>
<td>0.145</td>
<td>0.145</td>
</tr>
<tr>
<td>VARQ ($\tau_y = 0.5, \tau_r = 0.9, \tau_r = 0.5$)</td>
<td>0.984</td>
<td>0.153</td>
<td>0.153</td>
</tr>
<tr>
<td>VARQ ($\tau_y = 0.9, \tau_r = 0.5, \tau_r = 0.5$)</td>
<td>0.820</td>
<td>0.285</td>
<td>0.058</td>
</tr>
</tbody>
</table>

Table II evaluates the dynamic stability of all the different specifications. All eigenvalues modulus are inside the unit circle. The system is close to unit root for $\tau_x = 0.90$, which will produce a non-stationary behavior in the QIRF for this case.

The QIRF analysis shows that mean-based OLS and median responses show similar dynamics for both output and inflation. For output gap both responses are very similar and negative, while they are both negative for inflation but mean effects are larger than median ones.
The $\tau_y = 0.90$ output quantile path effects for output are close to zero. This determines that a dynamic path of extraordinary growth would not be affected by changes in the interest rate, although inflationary consequences would be bounded by those of the average effect.

The $\tau_y = 0.10$ output quantile path, however, shows a positive and persistent effect on output. As a result its cumulative effect is the largest. For inflation, however, it shows small effects similar to other quantiles. Thus, if the economy were to remain in a state of permanent recession, as given by persistent realizations in the lower 10th conditional quantile in output gap, increasing the interest rate by 1 std.dev. would increase the output by about 0.5 std.dev. in the long-run as compared to the value if the interest rate would not be changed.

When computing the same graphs for different fixed values of $\tau_\pi$ we observe considerable differences between the case for high and low inflation quantile paths. In particular the case for $\tau_\pi = 0.90$ shows a non-stationary behavior with persistent increasing negative effects on inflation (the maximum modulus eigenvalue in Table II is 0.984). This corresponds to a unit root behavior. On the other hand, when using $\tau_\pi = 0.10$ the curves show a positive accumulated effect on inflation.

The model thus highlights potential asymmetry in the dynamic propagation of shocks. The previous analysis determined that high and low quantiles are associated with more persistence and, in general, larger effects of a given monetary shock. This analysis should be combined with the analysis of non-linearity and structural changes in the mean and quantile dynamics. Nevertheless these simple linear models using different quantile paths can be used to evaluate extreme events even when we do not have enough observations to properly evaluate a structural change.

Another issue that is of interest is that while the VARQ model is monotonic on $\tau$, the QIRF effects are not. For instance, while the effects of increasing the interest rate are negative on inflation for the mean and the median, the calculated effects for the $\tau_y = 0.10$ are positive. Note that in general QR models are used to evaluate heterogeneous effects which are themselves the result of unobserved factors. As such, different quantile paths can be the result of omitted variables. In this case, low output quantiles together with a positive shock on the interest rate could be result of attracting foreign capital, which in turn has a positive impact on output with idle productive capacity.

6. CONCLUSION

To our knowledge this is the first attempt to construct IRFs from multivariate semiparametric directional quantiles. Within this framework we can explore dynamic heterogeneity in the potential effect of a given shock into the future performance of series.

The present article can be extended in several directions. First, we have addressed only linear QR models for each separate direction, and, as such, the VARQ model requires a simple matrix inversion. This model could be applied to nonlinear and nonparametric models for each direction, and the VARQ model would thus be a fixed-point solution to a nonlinear system of equations.

Second, the model should be further evaluated in terms of in-sample and out-sample dynamic forecasting. In particular, given fixed covariates for which we would like to forecast, random draws on the $m$-dimensional unit ball should be able to forecast the $m$-dimensional density. As QR provides a flexible model to construct univariate density estimations, the VARQ model could be applied to multivariate density frameworks.

Third, we can use the proposed model to evaluate potential structural breaks, as given by dynamic paths that correspond to extreme or unusual events. Quantile configurations based on a given sample can be used to forecast future events for which we do not have enough observations to analyze. That is, extreme events in the past, as given by high or low conditional quantiles provide a useful extrapolation method for future events.

ACKNOWLEDGEMENT

The author is grateful to the co-editor, Dr. David Stoffer, and to two anonymous referees for their constructive comments and suggestions.
DATA AVAILABILITY STATEMENT

STATA codes and data to apply the procedures in the empirical application and the Appendix are available at the permanent link http://gabrielmontes.com.ar/qirf.zip

REFERENCES


APPENDIX

Consider a two-variable model, that is $m = 2$,

\[ Y_{1t} = \beta_{11} Y_{1t-1} + \beta_{12} Y_{2t-1} + \alpha_1 + (1 + \delta_{11} Y_{1t-1} + \delta_{12} Y_{2t-1}) \varepsilon_{1t}, \]

\[ Y_{2t} = \beta_{21} Y_{1t-1} + \beta_{22} Y_{2t-1} + \alpha_2 + (1 + \delta_{21} Y_{1t-1} + \delta_{22} Y_{2t-1}) \varepsilon_{2t}. \]
Figure A1. IRF and QIRF simulations for $\tau_1 = 0.5$ and $\tau_2 \in \{0.1, 0.5, 0.9\}$.
Furthermore assume that \( \varepsilon_{ijt} \sim i.i.d.(0, \sigma_i) \), \( i, j = 1, 2 \). This corresponds to a reduced form VAR model. In quantile regression models there is a standard procedure to generate heterogeneity across quantiles that is to generate a ‘location-scale shift’ model where the covariates (i.e. \( Y_{1t-1} \) and \( Y_{2t-1} \) in our case) affect the variance (i.e. scale) of the model. As such, heteroskedasticity would imply that the mean-based model differ from that of quantiles. A model with \( \delta_{ij} = 0, \forall i, j = 1, 2 \), produces no heterogeneity in the quantile effects (a model known as a ‘location shift’ model). If on the other hand there is a pair \( i, j \) such that \( \delta_{ij} \neq 0 \), there will be heterogeneity in the quantile effects. In particular we have

\[
E(Y_{jt} | Y_{1t-1}, Y_{2t-1}) = \beta_{j1} Y_{1t-1} + \beta_{j2} Y_{2t-1} + \alpha_j,
\]

and

\[
Q_{Y_{jt}}(\tau_j | Y_{1t-1}, Y_{2t-1}) = (\beta_{j1} + \delta_{j1} F_j^{-1}(\tau_j)) Y_{1t-1} + (\beta_{j2} + \delta_{j2} F_j^{-1}(\tau_j)) Y_{2t-1} + (\alpha_j + F_j^{-1}(\tau_j)),
\]

for \( j = 1, 2 \), where \( F_j^{-1}(\tau_j) \) is the \( \tau_j \) quantile of \( \varepsilon_{jt} \). Note that, as noted above, the quantile marginal effects will vary if there is a pair \( i, j \) such that \( \delta_{ij} \neq 0 \).

Consider simulations of \( T = 10,000 \) observations with \( \alpha_1 = \alpha_2 = 1, \beta_{ij} = 0.25, \forall i, j = 1, 2, \varepsilon_{jt} \sim i.i.d. \text{Normal}(0,1) \), \( j = 1, 2 \), with different specifications of the parameters \( \delta_{ij} \). We simulate a unit change (shock) in variable 1 and compute IRF (i.e. OLS based VAR model) and QIRF simulations for \( \tau_1 = 0.5 \) and \( \tau_2 \in \{0.1, 0.5, 0.9\} \), using the proposed model in the paper. The QIRF corresponds to different fixed ‘quantile paths’ for a given pair \( (\tau_1, \tau_2) \) (Figure A1).